

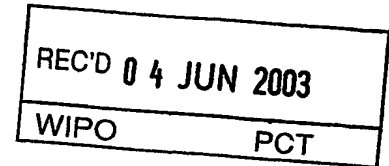
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Patentanmeldung Nr. Patent application No. Demande de brevet n°

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Anmelder/Applicant(s)/Demandeur(s):

SHELL INTERNATIONALE RESEARCH  
MAATSCHAPPIJ B.V.  
Carel van Bylandtlaan 30  
2596 HR Den Haag  
PAYS-BAS

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Steerable soil penetration system

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## STEERABLE SOIL PENETRATION SYSTEM

### BACKGROUND OF THE INVENTION

The invention relates to a steerable soil penetration system and method.

Such a system is known from US patent No. 5,163,520.

5 In the known system a steerable penetration head is pivotally connected to a string of tubulars that are interconnected by screw thread connectors and that are pushed in a substantially horizontal direction through a shallow subsurface soil layer by a hydraulic ram, which  
10 is mounted in a trench or pit. The ram pushes the tubing string and associated penetration head through the soil and when the last tubing section has been substantially inserted into the created hole the ram is pulled back whereupon a new tubing section is added to the tubular  
15 string which is then pushed into the hole, which sequence of adding a new tubing section to the string and inserting it into the hole is continued until the penetration head has reached its target.

Other steerable soil penetration systems are known  
20 from US patent Nos. 4,694,913; 5,070,948; 4,945,999; 4,306,626; 5,904,444; 5,878,825 and 4,981,181.

The aforementioned US patent 5,878,825 discloses a steerable penetration head which is rotatably connected to a chain of short and rigid tubular elements that are  
25 interconnected by joints that are rotatable about a single axis. The chain of rigid tubular elements is pushed into the hole pierced by the steerable penetration

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head by an injector formed by a hydraulic piston assembly at the bottom of an injector pitch.

Disadvantages of this known steerable soil penetration system are that the chain of rigid tubular elements interconnected by joints is complex, wear-prone, expensive and prone to buckling into a zig-zag configuration within the pierced hole, thereby significantly increasing the wall friction and inhibiting the penetration process. In addition, it requires a trench or pit.

An object of the present invention is to alleviate the disadvantages of this and other known soil penetration systems.

A further object of the present invention is to provide a system and method for creating a shallow hole in a subsurface formation, wherein a small diameter pilot hole is pierced into the formation which pilot hole is subsequently expanded to an encased larger diameter hole in which one or more fibre optical, electrical and/or other cables and/or fluid transportation conduits are inserted, or which hole may serve as a subsurface fluid transportation and/or drainage conduit.

A further object of the present invention is to provide a cost effective system and method for creating a grid of shallow holes in a subsurface formation in urban and other areas, in which holes strings of geophones and/or fibre optical sensing devices can be permanently inserted for monitoring seismic reflections and/or other geophysical effects during an extensive period of time, with a minimum impact on the environment at the earth surface.

SUMMARY OF THE INVENTION

In accordance with the present invention there is provided a steerable soil penetration system comprising a steerable penetration head which is connected to an elongate flexible tubing such that the orientation of the penetration head can be varied relative to the tubing and means for injecting the elongate flexible tubing into the hole pierced by the penetration head and for inducing the penetration head to extend the hole in a desired direction.

Preferably the means for injecting the tubing into the pierced hole comprises a tubing injector assembly which pushes the tubing into the pierced hole to provide thrust to the penetration head. In order to avoid buckling of the elongate flexible tubing when it pushes the penetration head forward the tubing preferably has an outer diameter, which is more than 80%, and more preferably more than 90%, of the largest outer width of the steerable penetration head.

In one embodiment the flexible tubing is provided with conduits and/or electric cables for supplying power to the steerable penetration head. Alternatively or additionally, the flexible tubing can be equipped with electrical cables or optical fibres for data communication to and from the steerable penetration head. Suitably, said conduits, cables and fibres can be embedded in the wall of the flexible tubing. A suitable composite flexible tubing with electrical power cables embedded in the wall is disclosed in International patent application WO 0175263. Alternatively the flexible tubing may be a coilable steel tubing which may consist of a pair of coaxial steel tubulars wherein the electrical or

other power and or transmission cables extend through the annular space between the inner and outer tubular.

5       The elongate flexible tubing surrounded by a narrow annulus also serves as a hole lining which protects the hole against caving-in throughout and optionally also after completion of the hole piercing process. Optionally the elongate flexible tubing remains in the pierced hole to serve as a permanent hole lining and may be circumferentially expanded by inflation and/or an  
10       expansion device such as a mandrel or tractor to increase the internal width of the hole lining and optionally of the hole itself. The elongate flexible tubing may be equipped with a staggered pattern of relatively weak spots and/or openings, which break open and/or widen up  
15       to reduce the forces required to circumferentially expand the tubing wall. Suitably, the elongate flexible tubing is a steel tubular in which a staggered array of longitudinal slots is present, which slots traverse at least part of the wall in a radial direction. The slots  
20       may be filled with an elastomeric or other plugging agent when the hole is being pierced, which agent is mechanically and/or chemically disintegrated when the tubing is circumferentially expanded after completion of the piercing process.

25       The steerable penetration head and/or flexible tubing may be provided with one or more repetitive shock generating devices for enhancing the penetration rate of the penetration head through the soil in particular during a final phase of the hole piercing process. Also a  
30       vibration and/or shock generating device can be provided to reduce friction of the flexible tubing in the hole. Both these devices can be powered through said conduits or cables.

Preferably the steerable penetration head comprises a sensor for detecting obstacles ahead of the penetration head, which sensor is connected to a steering mechanism that is capable of changing the orientation of the penetration head relative to the tubing such that the penetration head follows a curved trajectory to avoid detected obstacles. The steering mechanism preferably allows to steer the penetration head along a predetermined trajectory through the soil and to return to said predetermined trajectory after the penetration head has deviated from said trajectory to avoid a detected obstacle.

Suitably, the steerable penetration head comprises a tapered nose section having a central axis that can be pivoted in any direction relative to a longitudinal axis of the tubing by the steering mechanism. To this end the tapered nose section may be connected to the tubing by a bendable tubular steering section, which can be induced by the steering mechanism to alternately obtain a straight or a curved shape. Said bendable tubular steering section may comprise memory metal, bimetallic, or technical ceramic (PZT) components which deform in response to temperature variations or to electrical voltage and one or more heating elements or electrical sources that are configured to vary the temperature or voltage of said components such that the bendable tubular section either obtains a straight or a curved shape.

The bendable tubular steering section may either bend proportional or in an on/off non-proportional mode. In a suitable embodiment the bendable tubular steering section comprises at least three circumferentially spaced segments that are individually heated or cooled such that the lengths of the segments will vary and that the

bendable tubular section either obtains a straight or a curved shape. Alternatively, the bendable tubular steering section is at one side weakened by perforations, slits or otherwise such that it will bend in a predetermined direction under the axial compression force exerted by the elongate flexible tubing and a stiff sleeve is movably arranged adjacent to the bendable tubular section such that the sleeve can be moved within or around the bendable tubular section to force the section into a substantially straight position and which can be retrieved from the bendable tubular to induce the bendable tubular section to bend under the axial compression force exerted by the elongate flexible tubing.

The method according to the invention for piercing an at least partially horizontal hole in a subsurface formation with a steerable soil penetration system comprises the step of exerting a thrust force to a steerable penetration head by an elongate flexible tubing and/or downhole propulsion means thereby inducing the penetration head to extend the hole in a desired direction.

Optionally, at least part of the elongate flexible tubing is left behind in the pierced hole to serve as a permanent hole liner and at least part of the elongate flexible tubing may be circumferentially expanded after completion of the piercing process such that the expanding tubing radially expands the pierced hole to a larger internal width. The expansion process may create a predetermined pattern or track in the permanent hole liner, which could be used by the expansion device or tractor to propel itself forward.



DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

The foregoing and other features, objects, applications and effects of the method and system according to the invention will become more apparent from the following more detailed description of preferred  
5       embodiments of the invention in which reference is made to the accompanying drawings, in which:

Fig. 1 is schematic longitudinal sectional view of a shallow hole, which is being pierced into a subsurface  
10       formation by a steerable hole penetration system according to the invention;

Fig. 2 is a schematic longitudinal sectional view of the thus pierced hole in which an elongate flexible tubing is circumferentially expanded to increase the  
15       internal width of the hole; and

Fig. 3 is a more detailed longitudinal sectional view of the penetration head of the steerable hole penetration system shown in Fig. 1.

Referring now to Fig. 1, there is shown a steerable  
20       hole penetration system comprising a steerable penetration head 1, which is rotatably and pivotably connected to an elongate flexible tubing 2 by a steering mechanism 3. The tubing 2 is unreeled from a reeling drum 4 at the earth surface and pushed into the hole  
25       pierced by the penetration head 1 by a tubing injector assembly 6. Adjacent to the tubing injector assembly 6 a tubing guide pipe 7 is screwed in an inclined position into the topsoil. Alternatively said guide pipe 7 may be hammered or drilled into the topsoil. The guide pipe 7  
30       safeguards a stable and pressure tight launch pad for the flexible tubing 2 into the hole. After the soil has been removed from the interior of the tubing guide pipe 7 a wedge 9 is inserted near the bottom of said interior and

the penetration head 1 is pushed into the underlying earth formation 8 by the thrust exerted by the tubing injector assembly 6 via the tubing 2 to the penetration head 1.

5       The steering mechanism 3 is configured to orient the penetration head 1 either in a substantially aligned or in a slightly misaligned direction relative to the elongate flexible tube 2 in which case either substantially straight or slightly curved hole sections  
10       will be pierced.

Fig. 3 shows in more detail the penetration head 1 and steering mechanism 3 of the steerable hole penetration system of Fig. 1.

15       The steering mechanism 3 comprises a first tubular section 3A which is rotatably connected to a proximal end 2A of the elongate tubing 2 by a first hollow shaft 30 which is at one end connected to a first electrical motor and gear mechanism (not shown) inside the orientation control unit 31 and at another end to the  
20       first tubular section 3A by means of a series of radial spacers 32. The steering mechanism 3 furthermore comprises a second tubular section 3B which is rotatably connected to a slant proximal end 3C of the first tubular section 3A by a second hollow shaft 33 which co-axially  
25       surrounds the first hollow shaft 30 and which is at one end connected to a second electrical motor and gear mechanism (not shown) inside the orientation control unit 31 and at another end to the second tubular section 3B by means of a series of radial spacers 34.

30       Rotation of the second tubular section 3B relative to the first tubular section 3A of the steering mechanism 3 will as a result of the slant orientation of the proximal end 3C cause the penetration head 1 to obtain a slightly

deviated orientation relative to the central axis 35 of the elongate flexible tubing 2 in which case a slightly curved hole section is pierced. The angular orientation of the curved hole section relative to the central axis 35 is simultaneously controlled by rotating the first tubular section 3A relative to the proximal end 2A of the elongate flexible tubing 2. The steering mechanism 3 may be made of a composite shock absorbing material and/or comprise one or more shock absorbers (not shown).

Inside the first hollow shaft 30 and the orientation control unit 31 a central opening 36 is present in which an umbilical electrical cable bundle 37 is secured by means of a series of spacers 38. The central opening 35 also serves as a fluid injection conduit through which a lubricating and cooling liquid is injected into an annular space 40 between the elongate tubing 2 and the inner wall 41 of the pierced hole as illustrated by arrows 42. Preferably said liquid is injected at low speed into the annular space 40 in order to inhibit creation of wash outs of the pierced hole by jetting action.

The penetration head 1 is at least during an initial stage of the piercing process pushed forward through the subsurface formation 8 by the thrust exerted by the tubing 2, thereby compacting and/or pushing aside the formation in the immediate vicinity of the penetration head 1. When a substantial length of tubing 2 has been injected into the hole, friction between the tubing 2 and the inner surface 41 of the hole will reduce the thrust exerted to the penetration head 1. To stimulate the progress of the penetration process the penetration head 1 is vibrated in an axial direction relative to the

tubing 2 and steering mechanism 3 by means of a hammer 44 and anvil 45 assembly which are vibrated relative to the second tubular section 3B and relative to each other by means of an electromagnetic linear motor 46 and which  
5 receives electric power from the electric power cable bundle 37 via a inductive coupling 47. The inductive coupling 47 also provides electric power to an electronic sensing and control unit 48 which senses acoustic reflections of the impacts exerted by the penetration  
10 head 1 to the formation 8 in order to identify any obstacles within the formation 8 ahead of the penetration head 1. The inductive coupling 47 and electrical umbilical cable bundle 37 serves as bi-directional power and signal transmission umbilical between an electrical power and control unit (not shown) at the earth surface  
15 and the downhole electronic sensing and control unit 48 within the penetration head 1.

In the embodiment shown in Fig. 1 and 3 the penetration head 1 comprises a tapered main section in which a cylindrical nose section 1A is inserted such that  
20 the penetration head 1 is substantially rotational symmetrical to the central axis 35 of the penetration system. In an alternative embodiment the penetration head 1 may have a frontal surface that permanently has a  
25 slant orientation relative the central axis 35 such that the penetration head 1 will create a curved hole in which case the steering mechanism 3 may comprise a single rotatable section 3A only, or comprise an array of three circumferentially spaced, for example bi-metallic, memory  
30 metal, or voltage responsive PZT ceramic segments (not shown) which may individually contract away from or expand against the inner wall 41 to steer the penetration head 1 such that it follows a predetermined trajectory or

circumvents any subsurface obstacles 50 detected by the downhole sensing and control unit 48 and subsequently returns to said predetermined course as indicated by the dotted line 51 in Fig. 1.

5           Fig. 2. shows how after completion of the piercing process the elongate flexible tubing 2 is  
circumferentially expanded by an expansion device 55,  
which is pulled through the tubing 2 by winding a  
cable 56 around a drum 57. An electrical cable 59 and a  
10       flexible fluid transportation conduit 58 are  
simultaneously pulled into the expanded tubing 2 by the  
expansion device 55. The expansion device 55 may comprise  
an expansion mandrel and/or rollers and a traction unit  
(not shown), which propels the device 55 forward through  
15       the tubing 2. The tubing may comprise a staggered array  
of weak spots, which open up or expand during the  
expansion process. The traction unit may comprise spikes,  
which penetrate through the thus created openings to  
generate a sufficient thrust to the expansion device 55  
20       such that the tubing is expanded and the borehole width  
is simultaneously increased by the expanding tubing 2.

C L A I M S

1. A steerable soil penetration system, the system comprising:

- a steerable penetration head which is connected to an elongate flexible tubing such that the orientation of the penetration head can be varied relative to the tubing;  
5 and

- means for injecting the elongate flexible tubing into the hole pierced by the penetration head and for inducing the penetration head to pierce the hole in a desired  
10 direction.

2. The steerable soil penetration system of claim 1, wherein the means for injecting the penetration head into the hole comprises a tubing injector assembly which pushes the tubing into the pierced hole thereby providing thrust to the penetration head, and wherein the tubing  
15 has an outer diameter which is more than 80% of the largest outer width of the steerable penetration head.

3. The steerable soil penetration system of claim 1, wherein the system is provided with a pump for pumping lubricating fluid through the interior of the tubing and an annular space between the tubing and the surrounding  
20 soil.

4. The steerable soil penetration system of claim 1, wherein the tubing is provided with conduits, electrical  
25 cables and/or optical fibres for the supply of power and/or for data communication and/or for measuring stresses along at least a substantial part of the length of the tubing.

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5. The steerable soil penetration system of claim 1, wherein the steerable penetration head is provided with a repetitive shock generating device for enhancing the penetration of the penetration head through the soil.

5 6. The steerable soil penetration system of claim 5, wherein the repetitive shock generating device is actuated by an electrical actuator which is connected to an electrical source via an electrical conductor which extends through the interior or the wall of the tubing.

10 7. The steerable soil penetration system of claim 1, wherein the steerable penetration head comprises a sensor for detecting obstacles ahead of the penetration head which sensor is connected to a steering mechanism which is configured to change the orientation of the  
15 penetration head relative to the tubing such that the penetration head follows a curved trajectory to avoid detected obstacles.

8. The steerable soil penetration system of claim 7, wherein the steering mechanism is programmed to steer the  
20 penetration head along a predetermined trajectory through the soil and to return to said predetermined trajectory after the penetration head has deviated from said trajectory to avoid a detected obstacle.

9. The steerable soil penetration system of claim 1, wherein the steerable penetration head comprises a  
25 tapered nose section having a central axis that can be pivoted in any direction relative to a longitudinal axis of the tubing by the steering mechanism.

10. The steerable soil penetration system of claim 1, wherein the penetration head is connected to the tubing  
30 by a bendable tubular steering section which can be induced by the steering mechanism to alternately obtain a straight or a curved shape.

11. The steerable soil penetration system of claim 10, wherein the bendable tubular steering section comprises memory metal or bimetallic components and one or more heating elements that are configured to vary the temperature of said components such that the bendable tubular section either obtains a straight or a curved shape.

12. The steerable soil penetration system of claim 10 or 11, wherein the bendable tubular steering section comprises at least three circumferentially spaced segments, which segments can be individually heated or cooled such that the lengths of the segments will vary and that the bendable tubular section either obtains a straight shape or becomes curved in any predetermined orientation.

13. The steerable soil penetration system of claim 10, wherein the bendable tubular steering section is at one side weakened by perforations, slits or otherwise such that it will bend in a predetermined direction under the axial compression force exerted by the elongate flexible tubing and wherein a stiff sleeve is movably arranged adjacent to the bendable tubular section such that the sleeve can be moved within or around the bendable tubular section to force the section into a substantially straight position and which can be retrieved from the bendable tubular to induce the bendable tubular section to bend under the axial compression force exerted by the elongate flexible tubing.

14. The steerable soil penetration system of claim 1, wherein at least a substantial part of the elongate flexible tubing is configured to be circumferentially expanded after completion of the hole penetration process.



15. The steerable soil penetration system of claim 14, wherein the elongate flexible tubing is equipped with a staggered pattern of relatively weak wall segments that are configured to widen or open up during the

5 circumferential expansion process, thereby reducing the forces required to circumferentially expand the tubing.

16. A method of piercing an at least partially horizontal or inclined hole in a subsurface formation with a steerable soil penetration system comprising a steerable  
10 penetration head, wherein a thrust force is exerted to the steerable penetration head by an elongate flexible tubing and/or downhole propulsion means, thereby inducing the penetration head to pierce the hole in a desired direction.

15 17. The method of claim 16, wherein at least part of said thrust force is exerted on the penetration head by pushing the elongate flexible tubing into the pierced hole and the tubing has an outer diameter which is more than 80% of the largest outer width of the steerable  
20 penetration head and/or of the hole being pierced thereby.

18. The method of claim 16, wherein at least part of said thrust force is applied to the steerable penetration head by downhole propulsion means which comprises a downhole  
25 shock generator which hammers the penetration head forward through the subsurface formation during at least a final part of the hole piercing process.

19. The method of claim 17, whereby an electrical voltage is applied between the flexible tubing and the hole in  
30 such a way that polarization of any clay particles in the wall of the hole reduces any tubing-to-wall sticking tendency and decreases tubing-to-wall friction.

20. The method of claim 17, wherein at least part of the elongate flexible tubing is left behind in the pierced hole to serve a hole liner.

5 21. The method of claim 20, wherein at least part of the elongate flexible tubing is circumferentially expanded after completion of the piercing process such that the expanding tubing radially expands the pierced hole to a larger internal width.

10 22. The method of claim 21, wherein at least part of the elongate flexible tubing is circumferentially expanded by an expansion device which comprises an expansion cone and/or rollers that increase the internal width of the tubing when the device is moved in a longitudinal direction through the tubing and which expansion device  
15 simultaneously pulls one or more electric, fibre optical, fluid transportation and/or other conduits into the expanded section of the hole.

20 23. The method of any one of claims 16-22, wherein a string of geophones and/or fibre optical sensing devices is inserted into the pierced hole to monitor seismic reflections and/or other geophysical effects during an extensive period of time.

A B S T R A C T

STEERABLE SOIL PENETRATION SYSTEM

A steerable soil penetration system comprises a steerable penetration head, which is connected to an elongate flexible tubing such that the orientation of the penetration head can be varied relative to the tubing. The elongate tubing and/or a downhole hammer or tractor pushes the penetration head through the subsurface formation. Preferably the tubing is surrounded by a narrow annulus so that buckling of the tubing is inhibited and the tubing protects the pierced hole against caving in. Optionally the tubing is circumferentially expanded after completion of the piercing process thereby increasing the width of the pierced hole and providing a permanent hole lining.

(Fig. 1)

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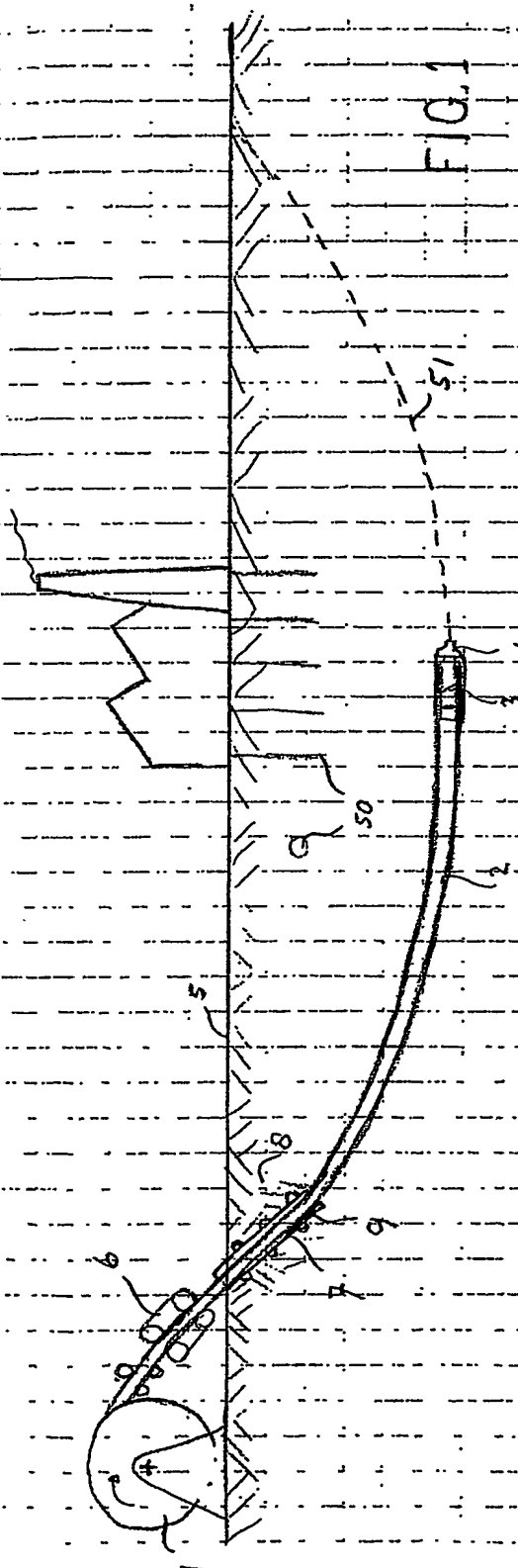


FIG. 1



FIG. 2

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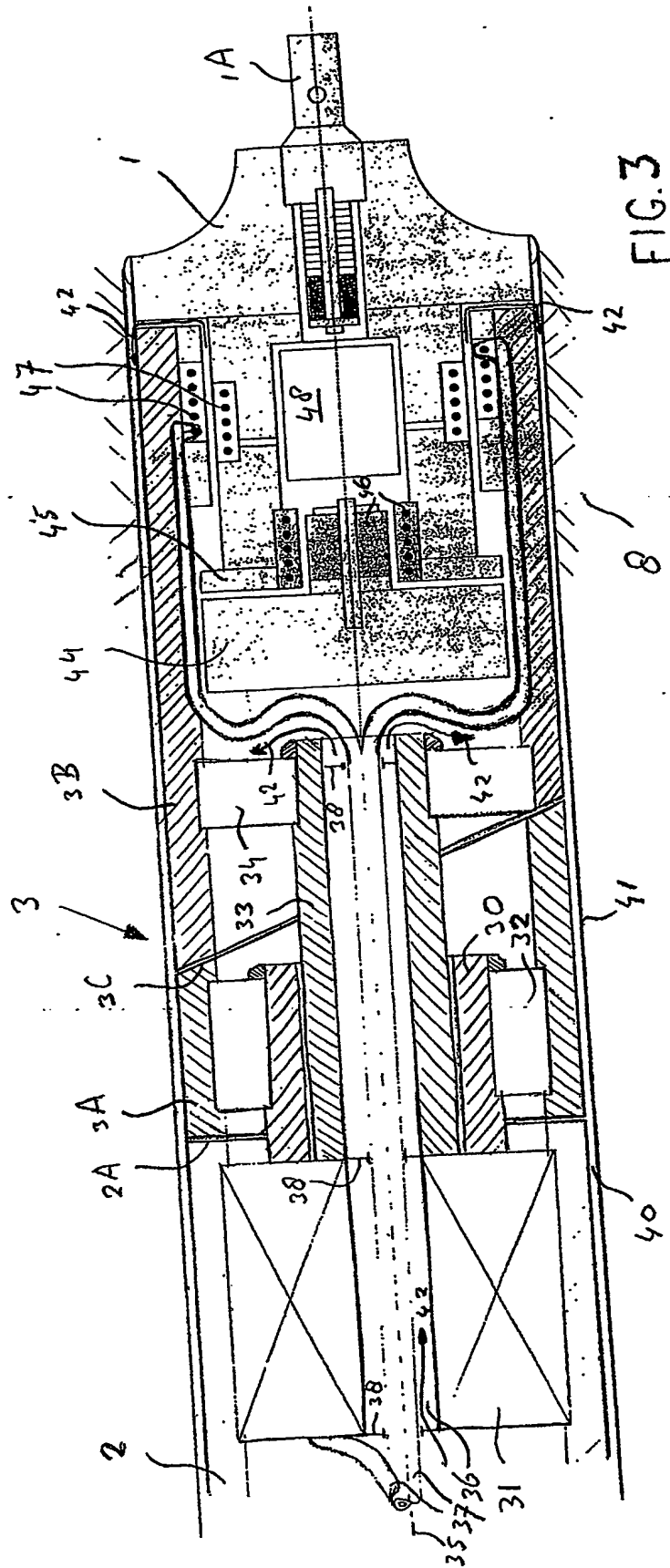


FIG. 3

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